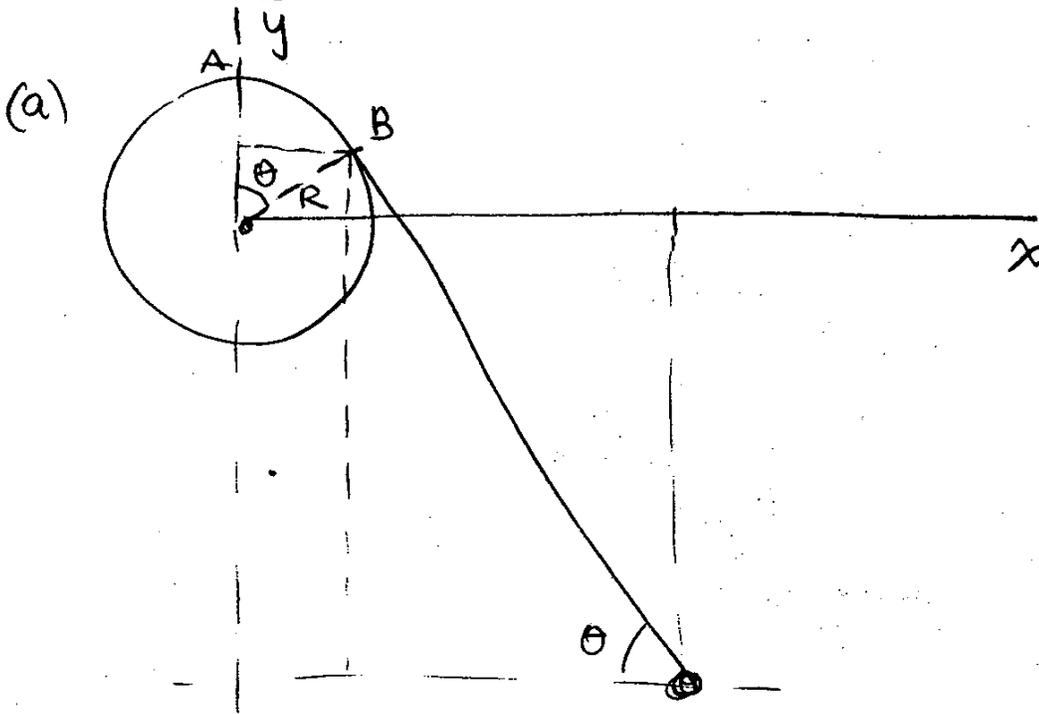


Problem 1 Mechanics

$$x = R \sin \theta + s \cos \theta$$

$$y = R \cos \theta - s \sin \theta$$

and $s + R\theta = \ell \rightarrow \dot{s} + R\dot{\theta} = 0$

$$\boxed{\dot{\theta} = -\frac{\dot{s}}{R}}$$

$$\begin{aligned} \dot{x} &= (R \cancel{\cos \theta} - s \sin \theta) \dot{\theta} + \dot{s} \cancel{\cos \theta} \\ &= \frac{s \dot{s}}{R} \sin \theta \end{aligned}$$

$$\begin{aligned} \dot{y} &= -(R \cancel{\sin \theta} + s \cos \theta) \dot{\theta} - \dot{s} \cancel{\sin \theta} \\ &= \frac{s \dot{s}}{R} \cos \theta \end{aligned}$$

$$\dot{x}^2 + \dot{y}^2 = \frac{s^2 \dot{s}^2}{R^2}$$

$$L = \frac{1}{2} m \frac{s^2 \dot{s}^2}{R^2}$$

$$(b) \quad p = \frac{\partial L}{\partial \dot{s}} = \frac{m s^2 \dot{s}}{R^2} \rightarrow \dot{s} = \frac{p R^2}{m s^2}$$

$$H = p \dot{s} - L = \frac{1}{2} m \frac{s^2 \dot{s}^2}{R^2}$$

$$H = \frac{1}{2} m \frac{s^2}{R^2} \frac{p^2 R^4}{m^2 s^4}$$

$$H = \frac{1}{2m} \frac{R^2}{s^2} p^2$$

$$\frac{\partial H}{\partial p} = \dot{s} = \frac{2H}{p}$$

$$\frac{\partial H}{\partial s} = -\dot{p} = -\frac{2H}{s}$$

$$\dot{p} = \frac{2H}{s}$$

Then

$$\frac{d}{dt} \left(\frac{p}{s} \right) = \frac{s \dot{p} - p \dot{s}}{s^2} = \frac{s \frac{2H}{s} - p \frac{2H}{p}}{s^2} = 0$$

$\left(\frac{p}{s} \right)$ is a constant of the motion

Indeed $H = E = \frac{R^2}{2m} \left(\frac{p}{s}\right)^2$

$$\boxed{\frac{p}{s} = \pm \frac{\sqrt{2mE}}{R}}$$

$$p \dot{s} = 2E$$

$$\pm s \cdot \frac{\sqrt{2mE}}{R} \dot{s} = \cancel{\sqrt{2E}} \sqrt{2E}$$

$$s \dot{s} = \pm \sqrt{\frac{2E}{m}} R$$

$$\frac{d}{dt} s^2 = \pm 2 \sqrt{\frac{2E}{m}} R$$

$$\boxed{s^2(t) = \pm \sqrt{\frac{8E}{m}} R t + s_0^2}$$

$$[Q_i, P_j] = \delta_{ij}$$

(c) $Q = s^2$

$$P = \frac{p}{\beta s}$$

$$dQ \wedge dP = (2s ds) \wedge \frac{1}{\beta} \frac{s dp - p ds}{s^2}$$

$$= \frac{2s ds}{\beta} \wedge \frac{s dp}{s^2}$$

$$= \frac{2}{\beta} ds \wedge dp$$

need $\beta = 2$

$Q = s^2$
$P = \frac{p}{2s}$

then $H = \frac{1}{2m} R^2 \left(\frac{p}{s}\right)^2 = \frac{1}{2m} R^2 (2P)^2$

$H' = \frac{2}{m} R^2 P^2$

New hamiltonian

With $H(p, q)$

HJ $\frac{\partial S}{\partial t} = -H\left(\frac{\partial S}{\partial q}, q\right)$

Thus we have

$\frac{\partial S}{\partial t} = -\frac{2}{m} R^2 \left(\frac{\partial S}{\partial Q}\right)^2$

$S = S(Q, t)$

$$S = W(Q) - \alpha t$$

$$-\alpha = -\frac{2}{m} R^2 \left(\frac{\partial W}{\partial Q} \right)^2$$

$$\left(\frac{dW}{dQ} \right)^2 = \frac{\alpha m}{2 R^2} \rightarrow \boxed{\frac{dW}{dQ} = \pm \sqrt{\frac{\alpha m}{2}} \frac{1}{R}}$$

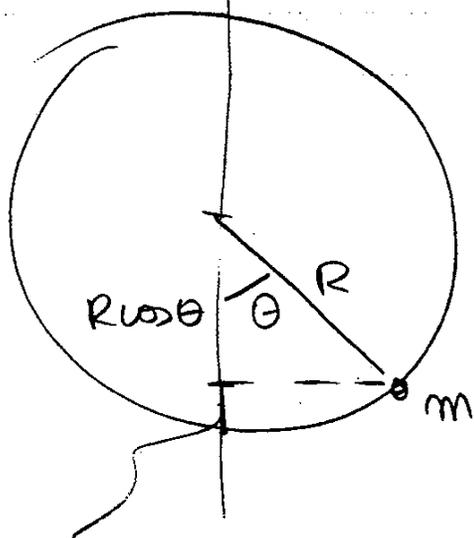
$$W(Q) = \pm \sqrt{\frac{\alpha m}{2}} \frac{Q}{R}$$

$$\boxed{S(Q, t, \alpha) = \pm \sqrt{\frac{\alpha m}{2}} \frac{Q}{R} - \alpha t}$$

$$\frac{\partial S}{\partial \alpha} = \beta = \text{constant}$$

$$\pm \frac{1}{2} \sqrt{\frac{m}{2\alpha}} \frac{Q}{R} - t = \beta$$

$$\boxed{Q = \pm \sqrt{\frac{8\alpha}{m}} R t \pm \sqrt{\frac{8\alpha}{m}} R \beta}$$

Mechanics 2

$$R(1 - \omega \theta)$$

$$\vec{v} = R\dot{\theta} \vec{e}_\theta + \omega R \sin \theta \vec{e}_\phi$$

$$(a) L = T - V$$

$$= \frac{1}{2} m (R\dot{\theta} \vec{e}_\theta + \omega R \sin \theta \vec{e}_\phi)^2 - mgR(1 - \omega \theta)$$

since constants are irrelevant (in the V term)

$$L = \frac{1}{2} m (R^2 \dot{\theta}^2 + \omega^2 R^2 \sin^2 \theta) + mgR \omega \theta \quad \checkmark$$

$$L = \frac{1}{2} m R^2 \dot{\theta}^2 + \underbrace{\frac{1}{2} m \omega^2 R^2 \sin^2 \theta + mgR \omega \theta}_{-V_{\text{eff}}}$$

$$V_{\text{eff}} = -\frac{1}{2} m R^2 \omega^2 \sin^2 \theta - mgR \omega \theta \quad \checkmark$$

$$(b) \quad \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\theta}} \right) = \frac{\partial L}{\partial \theta}$$

$$\frac{1}{2} m R^2 \cdot 2 \ddot{\theta} = m \omega^2 R^2 \sin \theta \cos \theta - m g R \sin \theta$$

$$m R^2 \ddot{\theta} = -m g R \sin \theta + m \omega^2 R^2 \sin \theta \cos \theta$$

$$\ddot{\theta} = -\frac{g}{R} \sin \theta + \omega^2 \sin \theta \cos \theta \quad \checkmark$$

$$(c) \quad \theta = \text{constant} \rightarrow \dot{\theta} = 0, \rightarrow \ddot{\theta} = 0$$

$$-\frac{g}{R} \sin \theta + \omega^2 \sin \theta \cos \theta = 0$$

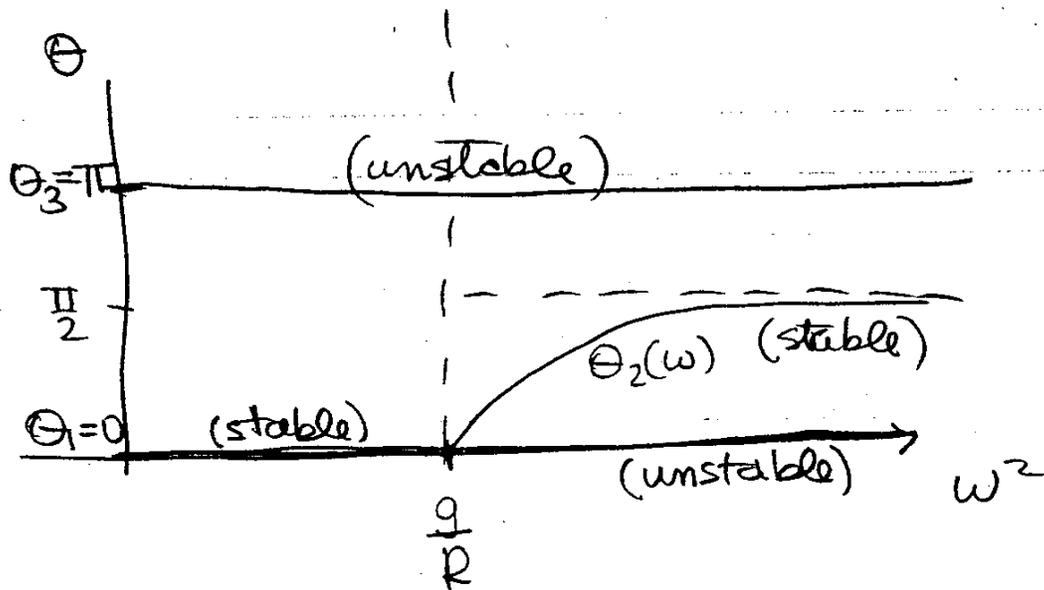
$$\sin \theta \left(\omega^2 \cos \theta - \frac{g}{R} \right) = 0$$

Three solutions

$$\begin{aligned} \theta_1 &= 0 \\ \theta_2 &= \cos^{-1} \left(\frac{g}{R \omega^2} \right) \\ \theta_3 &= \pi \end{aligned}$$

θ_2 requires $\omega^2 > \frac{g}{R}$

So 2 θ 's for $\omega^2 < \frac{g}{R}$
 3 θ 's for $\omega^2 > \frac{g}{R}$



$$(d) \quad \frac{1}{2} m R^2 2\ddot{\theta} = - \frac{\partial V_{\text{eff}}}{\partial \theta}$$

$$\boxed{m R^2 \ddot{\theta} = - \frac{\partial V_{\text{eff}}}{\partial \theta}}$$

Equilibrium points θ_i satisfy $\left. \frac{\partial V_{\text{eff}}}{\partial \theta} \right|_{\theta_i} = 0$

So for $\theta = \theta_i + \epsilon$ we set

$$m R^2 \ddot{\epsilon} = - \left\{ \left. \frac{\partial V}{\partial \theta} \right|_{\theta_i} + \epsilon \left. \frac{\partial^2 V}{\partial \theta^2} \right|_{\theta_i} \right\}$$

$$\boxed{m R^2 \ddot{\epsilon} = - \epsilon \left. \frac{\partial^2 V}{\partial \theta^2} \right|_{\theta_i}}$$

$$\Rightarrow \Omega_i^2 \equiv \frac{1}{m R^2} \left. \frac{\partial^2 V}{\partial \theta^2} \right|_{\theta_i} \quad \text{for stability } \Omega_i^2 > 0$$

↑
oscillation frequency

$$\frac{\partial V}{\partial \theta} = -\frac{1}{2} m R^2 \omega^2 2 \sin \theta \cos \theta + m g R \sin \theta$$

$$= -m R^2 \omega^2 \sin \theta \cos \theta + m g R \sin \theta$$

$$\frac{\partial^2 V}{\partial \theta^2} = -m R^2 \omega^2 (\cos^2 \theta - \sin^2 \theta) + m g R \cos \theta$$

$$= -m R^2 \omega^2 (2 \cos^2 \theta - 1) + m g R \cos \theta$$

$$\left. \frac{1}{m R^2} \frac{\partial^2 V}{\partial \theta^2} \right|_{\theta_i} = -\omega^2 (2 \cos^2 \theta_i - 1) + \frac{g}{R} \cos \theta_i$$

1) $\theta_1 = 0$ $\Omega_1^2 = -\omega^2 (2 - 1) + \frac{g}{R}$

$\Omega_1^2 = \frac{g}{R} - \omega^2$ ✓

stable for $\omega < \sqrt{\frac{g}{R}} = \omega_0$
 unstable for $\omega > \sqrt{\frac{g}{R}} = \omega_0$

2) $\theta_2 = \cos^{-1} \frac{g}{R \omega^2}$ $\cos \theta_2 = \frac{g}{R \omega^2}$

$$\Omega_2^2 = -\omega^2 \left(2 \frac{g^2}{R^2 \omega^4} - 1 \right) + \frac{g^2}{R^2 \omega^2}$$

$$= \omega^2 - \frac{g^2}{R^2 \omega^2}$$

$$\Omega_2^2 = \omega^2 - \frac{g^2}{R^2 \omega^2}$$

Stable when $\omega^2 > \frac{g^2}{R^2 \omega^2}$ or $\omega^2 > \frac{g}{R}$

→ stable when it exists!

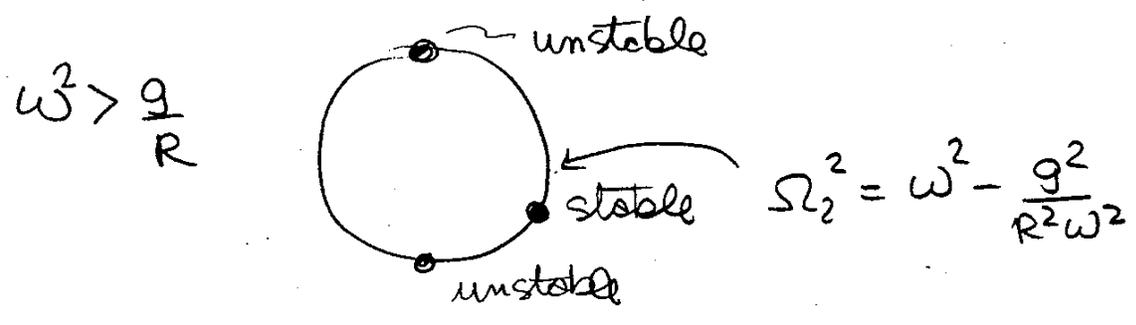
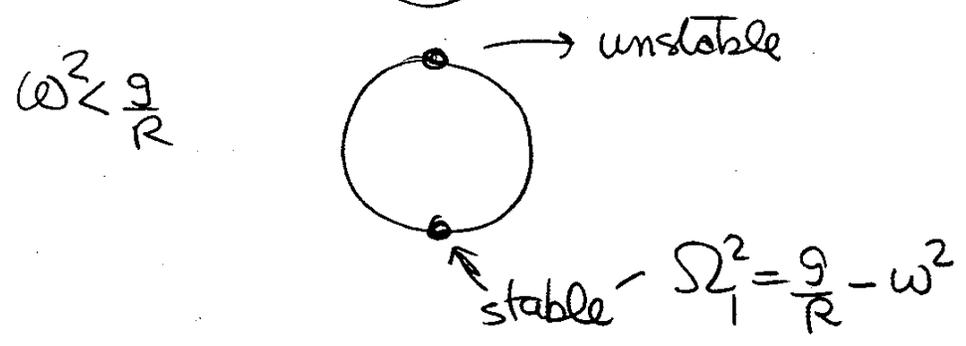
3) $\Theta_3 = \pi$

$$\Omega_3^2 = -\omega^2(2-1) - \frac{g}{R}$$

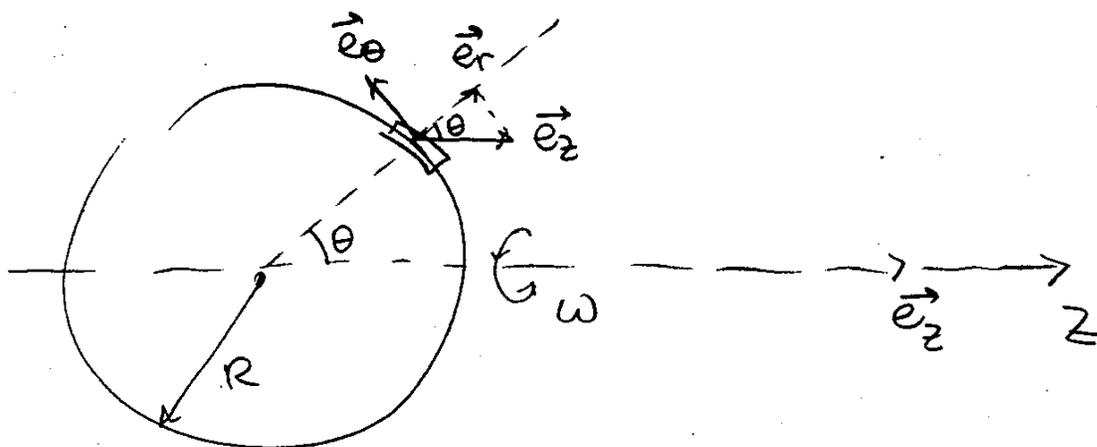
$$\Omega_3^2 = -\omega^2 - \frac{g}{R}$$

Always unstable, no oscillations

Regions of stability and instability indicated in the figure (p.3).



Electromagnetism Problem 1



$$(a) \quad \vec{B}_{in} = B_0 \vec{e}_z = B_0 (\vec{e}_r \cos \theta - \vec{e}_\theta \sin \theta)$$

$$\vec{B}_{out} = \frac{2m\omega \sin \theta}{r^3} \vec{e}_r + \frac{m \sin \theta}{r^3} \vec{e}_\theta$$

Continuity of the radial field

$$\frac{2m\omega \sin \theta}{r^3} = B_0 \omega \sin \theta$$

$$\boxed{B_0 = \frac{2m}{R^3}}$$

Current K per unit length ↗

$$\vec{K} = \sigma v(\theta) \vec{e}_\phi$$

$$= \frac{Q}{4\pi R^2} (R \sin \theta) \omega = \frac{Q\omega}{4\pi R} \sin \theta \vec{e}_\phi$$

$$= K_\phi \vec{e}_\phi$$

Discontinuity across the current sheet:

$$B_{\theta}(\text{out}) - B_{\theta}(\text{in}) = \frac{4\pi}{c} K_{\phi}$$

$$\rightarrow \frac{m \sin \theta}{R^3} + B_0 \sin \theta = \frac{Q\omega}{cR} \sin \theta$$

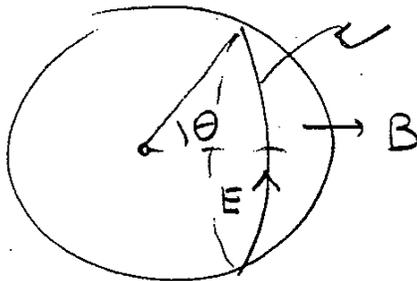
$$\frac{m}{R^3} + \frac{2m}{R^3} = \frac{Q\omega}{cR}$$

$$\frac{3m}{R^2} = Q \frac{\omega}{c} \rightarrow \boxed{m = \frac{1}{3} \left(\frac{\omega R}{c}\right) RQ} \checkmark$$

$$\boxed{m = \frac{1}{3} \left(\frac{\omega Q}{c}\right) R^2} \checkmark$$

$$\boxed{B_0 = \frac{2}{3} \frac{\omega}{c} \frac{Q}{R}} \checkmark$$

(b)



Apply Faradays law to this loop

$$\nabla \times E = -\frac{1}{c} \frac{\partial B}{\partial t}$$

$$\oint E \cdot d\mathbf{l} = -\frac{1}{c} \frac{\partial}{\partial t} (B \cdot \text{Area})$$

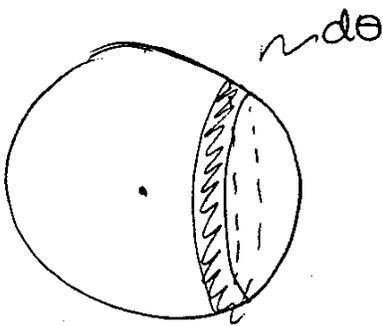
$$2\pi |E_{\phi}| R \sin \theta = \frac{1}{c} \left(\frac{dB_0}{dt}\right) \pi R^2 \sin^2 \theta$$

$$\therefore |E_{\phi}| = \frac{1}{2c} \frac{dB_0}{dt} R \sin \theta$$

$$= \frac{1}{2c} \frac{2}{3} \frac{\dot{\omega}}{c} \frac{Q}{R} R \sin \theta$$

$$\boxed{|E_{\phi}| = \frac{1}{3} \frac{Q \sin \theta}{c^2} \dot{\omega}} \checkmark \quad \text{--- sign}$$

(c) The torque tends to slow down the ball



$$dq = \frac{Q}{4\pi R^2} da = \frac{Q}{4\pi R^2} (R d\theta) 2\pi R \sin\theta$$

$$= \frac{Q}{4\pi} (2\pi) \sin\theta d\theta$$

$$dq = \frac{Q}{2} \sin\theta d\theta$$

$$dF = E_p(\theta) dq$$

$$= \frac{1}{3} \frac{Q \sin\theta}{c^2} \dot{\omega} \frac{Q}{2} \sin\theta d\theta$$

$$dF = \frac{1}{6} \frac{Q^2 \dot{\omega}}{c^2} \sin^2\theta d\theta$$

$$dG = dF \cdot R \sin\theta$$

$$\boxed{dG = \frac{1}{6} \frac{Q^2 \dot{\omega}}{c^2} R \sin^3\theta d\theta}$$

$$\int d\theta \sin^3\theta = \frac{4}{3}$$

$$\boxed{\vec{G} = -\frac{2}{9} \frac{Q^2 R}{c^2} \dot{\omega} \vec{e}_z}$$

↓
✓

(d)

$$\frac{d\vec{L}}{dt} = \vec{G}$$

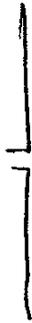
$$\frac{d(I\omega)}{dt} = G_{\text{ext}} - \frac{2}{9} \frac{Q^2 R}{c^2} \dot{\omega}$$

$$\textcircled{a} \quad I_{\text{mech}} \dot{\omega} + \frac{2}{9} \frac{Q^2 R}{c^2} \dot{\omega} = G_{\text{ext}}$$

so we read:

$$\boxed{I_{\text{mag}} = \frac{2}{9} \frac{Q^2 R}{c^2}} \quad \checkmark$$

Problem 2 E & M



$$a) \quad I(z, t) = I_0 \left(1 - \frac{\alpha_0 |z|}{d} \right) \cos \omega t$$

$$\text{For } |z| = \frac{d}{2} \text{ need } I(z, t) = 0$$

$$\rightarrow \boxed{\alpha_0 = 2}$$

$$I(z, t) = I_0 \left(1 - \frac{z}{d} \right) \cos \omega t \quad z > 0$$

$$I_0 \left(1 + \frac{\alpha_0 z}{d} \right) \cos \omega t \quad z < 0$$

Charge conservation $\nabla \cdot \mathbf{J} + \frac{\partial \rho}{\partial t} = 0$

Here

$$\frac{dI}{dz} + \frac{d\lambda(z, t)}{dt} = 0$$

$$\frac{d\lambda}{dt}(z, t) = - \frac{dI}{dz} = \begin{cases} \frac{2I_0}{d} e^{i\omega t} \\ -\frac{2I_0}{d} e^{-i\omega t} \end{cases}$$

$$\lambda(z) = \frac{2I_0}{-i\omega d} \quad z > 0$$

$$-\frac{2I_0}{-i\omega d} \quad z < 0$$

$$\lambda(z) = \pm \frac{2iI_0}{\omega d} \quad \begin{cases} z > 0 \\ z < 0 \end{cases}$$

(b)

$$\vec{P} = P_z \vec{e}_z$$

$$P_z = \int_{-d/2}^{d/2} z \lambda(z) dz$$

$$= 2 \int_0^{d/2} z \left(\frac{2iI_0}{\omega d} \right) dz$$

$$\vec{P} = \frac{4iI_0}{\omega d} \cdot \frac{z^2}{2} \Big|_0^{d/2} = \frac{iI_0 d}{2\omega} \vec{e}_z$$

$$\vec{P} = \frac{iI_0 d}{2\omega} \vec{e}_z \quad \frac{\omega}{c} = k$$

$$P_{\text{center-fed}} = \frac{ck^4}{3} |\vec{P}|^2 = \frac{ck^4}{3} \frac{I_0^2 d^2}{4c^2 k^2}$$

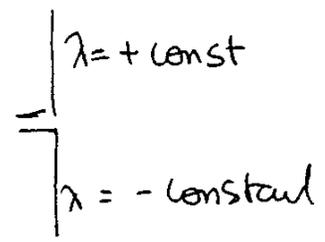
$$P_{\text{center-fed}} = \frac{I_0^2 (kd)^2}{12c}$$

(c) No magnetic dipole term since ✓

$$\vec{x} \times \vec{J} = 0 \text{ on the antenna (origin at \#)}$$



No electric quadrupole since the charge distribution



has no quadrupole term

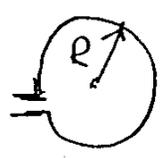
$$Q_{\alpha\beta} = \int (3x_\alpha x_\beta - r^2 \delta_{\alpha\beta}) \rho(x) d^3x$$

only $z \neq 0$

$$\int r^2 \rho(x) = 0 \text{ by symmetry}$$

$$\text{and } \int z^2 \rho(x) = 0 \quad \checkmark$$

(d) Now wrap the wire



$$2\pi R = d \quad R = \frac{d}{2\pi}$$

$$\text{Area } \pi R^2 = \pi \frac{d^2}{4\pi^2} = \frac{d^2}{4\pi}$$

$$m = \frac{I_0 d^2}{4\pi c}$$

$$\text{Power, circle} = \frac{c k^4 I_0^2 d^4}{3 \cdot 16\pi^2 c^2}$$

$$P_{\text{circle}} = \frac{I_0 (kd)^4}{(4\pi^2) 12 c}$$

$$\frac{P_{\text{circle}}}{P_{\text{center fed}}} = \frac{(kd)^4}{(kd)^2 (2\pi)^2}$$

$$\frac{P_{\text{circle}}}{P_{\text{center fed}}} = \left(\frac{1}{2\pi} kd\right)^2 = \left(\frac{d}{\lambda}\right)^2$$

$$\frac{P_{\text{circle}}}{P_{\text{center fed}}} = \left(\frac{d}{\lambda}\right)^2$$

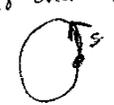
It is indeed very small. Electric dipole is leading term in radiation.

(e) In this case $\rho(\theta) = 0$ ^{NO!} since $I(\theta)$ is constant. So there is no dipole nor quadrupole term.

$$\rho = \frac{1}{r^2} \delta(r - \frac{d}{2\pi}) \delta(\phi - \frac{\pi}{2})$$

$$\Rightarrow \text{Dipole}$$

← this is wrong.
 $\frac{dI}{ds} = 0$ along circle,
 no charge, no moments



once you give a finite thickness to the wire there is no δ . This is mathematical abstraction.

Solution to SM1.

$$e^{-\frac{F}{kT}} = \sum e^{-\frac{E}{kT}} = \prod_{r=1}^{\infty} \frac{1}{1 - e^{-\frac{k\omega_0}{kT} r}}$$

$$F = kT \sum_{r=1}^{\infty} \ln(1 - e^{-\frac{k\omega_0}{kT} r})$$

$$\approx kT \int_0^{\infty} \ln(1 - e^{-x}) \frac{kT}{k\omega_0} dx$$

$$\text{Integral} = - \int_0^{\infty} (e^{-x} + \frac{e^{-2x}}{2} + \dots) dx = -\frac{\pi^2}{6}$$

$$\text{so } F = -\frac{\pi^2}{6} \frac{(kT)^2}{k\omega_0}$$

$$S = -\frac{dF}{dT} = \frac{\pi^2}{3} k \frac{kT}{k\omega_0}$$

$$E = F + TS = +\frac{\pi^2}{6} \frac{(kT)^2}{k\omega_0}$$

$$\sqrt{\frac{E}{k\omega_0}} = \frac{\pi}{\sqrt{6}} \frac{kT}{k\omega_0}, \quad S = \pi \sqrt{\frac{2}{3}} k \sqrt{\frac{E}{k\omega_0}}$$

Now identify S_N with $k \ln p(N)$ and E_N with $k\omega_0 N$
which gives $p(N) \sim e^{\frac{\pi \sqrt{2N}}{3}}$ We would not expect

to get anything beyond the exponent of the H-R formula
this way, without ~~the~~ calculating fluctuations in the canonical
ensemble (at least)

b) The time $\frac{E}{k\omega_0} = \sqrt{N}$, $S = k \ln(N)$
 $= k\pi \sqrt{\frac{2N}{3}}$

so $S = \pi \sqrt{\frac{2}{3}} k \frac{E}{k\omega_0}$

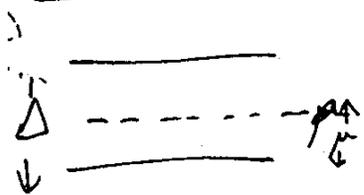
$\frac{dS}{dE} = \frac{1}{T}$ so $T = \frac{1}{\pi \sqrt{\frac{3}{2}} \frac{k\omega_0}{k}}$, independent of E .
 $\frac{dE}{kT_0}$

This is a system with a density of states $\sim e$

Clearly the canonical ensemble is only defined for $\frac{1}{kT} \gg \frac{1}{kT_0}$
 $\Rightarrow T \ll T_0$.

If we used it as a heat bath in contact with a smaller system, the small system will ~~be~~ ^{always} go into a canonical ensemble at temperature T_0 .

Solution to S.M.2



Assume the chemical potential is in the gap

Number in valence band is $\frac{N}{e^{\frac{\mu}{kT}} + 1} = N - \frac{N}{e^{\frac{\mu}{kT}} + 1}$

Number in conduction band is $\frac{N}{e^{\frac{\mu}{kT}} + 1}$

so μ must be halfway between bands (# of holes = # of excited electrons)

and $N_{\text{cond}} = \frac{N}{e^{\frac{\Delta}{2kT}} + 1}$, $N_{\text{val}} = \frac{N}{e^{\frac{\Delta}{2kT}} + 1}$

) Rate of upward transitions is proportional to N_{val}^2 , and to $N - N_{\text{conduction}}$ i.e. to N_{val} , and to the Bose-Einstein occupation factor $\frac{1}{e^{\frac{\Delta}{kT}} - 1}$ for the number of photons, energy Δ available to be absorbed.

Rate of downward transitions is proportional to N_{cond} and $N - N_{\text{val}}$ i.e. N_{cond} and to the factor $1 + \frac{1}{e^{\frac{\Delta}{kT}} - 1} = \frac{e^{\frac{\Delta}{kT}}}{e^{\frac{\Delta}{kT}} - 1}$ for spontaneous plus stimulated emission.

In Equilibrium if $N_{\text{cond}} e^{\frac{\Delta}{kT}} = N_{\text{val}}^2$, $\frac{N_{\text{cond}}}{N_{\text{val}}} = e^{-\frac{\Delta}{2kT}}$ ✓

[Constants in rates \uparrow and \downarrow other than those described above are same in each direction]

$$c) \text{ Now get } N_{\text{cond}} = \frac{N}{\Delta} \int_{-\Delta}^{\Delta} \frac{dE}{e^{\frac{E-\mu}{T}} + 1} = N_{\text{cond}} = \frac{N}{e^{\frac{\mu}{T}} + 1}$$

Assume $\frac{\Delta}{T} \gg 1$ and μ a gap. Then approximate by

$$\frac{N}{\Delta} \int_{-\Delta}^{\Delta} dE e^{\frac{\mu-E}{T}} = N e^{-\frac{\mu}{T}}$$

$$e^{-\frac{2\mu}{T}} = \frac{T}{\Delta} (e^{-\frac{\Delta}{T}} - e^{-\frac{2\Delta}{T}}) \quad \left[e^{\frac{2\mu-\Delta}{T}} = \frac{\Delta}{T} \right]$$

$$2\mu = \Delta \left(1 + \frac{T}{\Delta} \ln \frac{\Delta}{T} \right) \quad \text{so as } \frac{T}{\Delta} \rightarrow 0, \quad \mu \rightarrow \frac{\Delta}{2}$$

$$N_{\text{cond}} = N e^{-\frac{\mu}{T}} = N e^{-\frac{\Delta}{2T}} \sqrt{\frac{T}{\Delta}}$$

[Calculation in brackets only needed to check that μ is in middle of gap]

QM1. Solution

a) $|\psi\rangle$ is sum of states with $S_z^{tot} = \pm \frac{3}{2} \hbar$. Allowed values

of S ($S^2 = S(S+1)\hbar^2$) are $\frac{1}{2}, \frac{3}{2}$.

$S_z = \pm \frac{3}{2}$ can only belong to $S = \frac{3}{2}$ $\hookrightarrow (S^{tot})^2 |\psi\rangle = \frac{15}{4} \hbar^2 |\psi\rangle$

b) $S_x + iS_y$ increases S_z by 1

so R increases S_z^{tot} by 3. Only non-zero

matrix element is $\langle S_z^{tot} = \frac{3}{2} | R | S_z^{tot} = -\frac{3}{2} \rangle$

i.e. $\langle \frac{1}{2} \frac{1}{2} \frac{1}{2} | R | -\frac{1}{2} -\frac{1}{2} -\frac{1}{2} \rangle$

Thus $R | -\frac{1}{2} -\frac{1}{2} -\frac{1}{2} \rangle = a | \frac{1}{2} \frac{1}{2} \frac{1}{2} \rangle$

Since $(S_x^{(1)} + iS_y^{(1)}) | -\frac{1}{2} \rangle = | +\frac{1}{2} \rangle$ and there are 6 terms
in R that send $--- \rightarrow +---$, $a = 6$

In the same way $R^\dagger | \frac{1}{2} \frac{1}{2} \frac{1}{2} \rangle = 6 | -\frac{1}{2} -\frac{1}{2} -\frac{1}{2} \rangle$

and so $R |\psi\rangle = -6 |\psi\rangle$

Clearly $R(|+++ \rangle + |--- \rangle) = +6 |\psi\rangle$

and R on all other states (6) is zero.

$$\begin{aligned} \Rightarrow AB &= (\sigma_x \sigma_y)^{(1)} (\sigma_y \sigma_x)^{(2)} (\sigma_y \sigma_y)^{(3)} \\ BA &= (\sigma_y \sigma_x)^{(1)} (\sigma_x \sigma_y)^{(2)} (\sigma_y \sigma_y)^{(3)} \end{aligned}$$

2 pairs anticommute so $AB = BA$

and in same way $AC = CA$ ~~$AD = DA$~~ $BC = CB$

$$AD = (\sigma_x \sigma_x)^{(1)} (\sigma_y \sigma_x)^{(2)} (\sigma_y \sigma_x)^{(3)}$$

$$DA = (\sigma_x \sigma_x)^{(1)} (\sigma_x \sigma_y)^{(2)} (\sigma_x \sigma_y)^{(3)}$$

Again 2 pairs anticommute so $AD = DA$

$$\begin{aligned} ABCD &= (\sigma_x \sigma_y \sigma_y \sigma_x)^{(1)} (\sigma_y \sigma_x \sigma_y \sigma_x)^{(2)} (\sigma_y \sigma_y \sigma_x \sigma_x)^{(3)} \\ &= 1^{(1)} (-1)^{(2)} (1)^{(3)} = -1 \end{aligned}$$

$$d) \quad \sigma_x |\pm \frac{1}{2}\rangle = |\mp \frac{1}{2}\rangle \quad \sigma_y |\pm \frac{1}{2}\rangle = \pm i |\mp \frac{1}{2}\rangle$$

$$\text{so } A |+++ \rangle = - |--- \rangle$$

$$A |\psi \rangle = |\psi \rangle$$

$$A |--- \rangle = - |+++ \rangle$$

$$\text{and } B |\psi \rangle = |\psi \rangle \quad C |\psi \rangle = |\psi \rangle$$

$$D |+++ \rangle = |--- \rangle$$

$$\text{so } D |\psi \rangle = - |\psi \rangle$$

$$D |--- \rangle = |+++ \rangle$$

(agrees with $\lambda = -1$ above)

c) Measure $S_x^{(1)} S_y^{(2)} S_y^{(3)}$. Because $A = +1$,

results must be $\pm \frac{1}{2} \hbar, \pm \frac{1}{2} \hbar, \pm \frac{1}{2} \hbar$ with signs ~~+~~

{
+++
+--
-+-
---+

Measure $S_x^{(1)} S_x^{(2)} S_x^{(3)}$ must get signs

{
-++
+-+
+ +-

Solution to QM2

$$a) \quad \psi_1(\vec{x}) \sim e^{i\vec{k} \cdot \vec{x}} + f_1(\hat{x}) \frac{e^{ikr}}{r}$$

$$\psi_0(\vec{x}) \sim f_0(\hat{x}) \frac{e^{ikr}}{r} \quad \frac{\hbar^2 k'^2}{2m} = \frac{\hbar^2 k^2}{2m} + \Delta$$

$l=0$ scattering only, since scatter has no angular momentum,

f_1 and f_0 are both independent of \hat{x} .

Plane wave has flux $\frac{\hbar k}{m}$ per unit area,

f_1 corresponds to " $|f_1|^2 \frac{\hbar k}{m r^2}$ so total through sphere $\frac{\hbar k}{m} 4\pi |f_1|^2$

f_0 " " $|f_0|^2 \frac{\hbar k'}{m r^2}$, total $\frac{\hbar k'}{m} 4\pi |f_0|^2$

$$\text{so } \sigma_{el} = 4\pi |f_1|^2 \quad \sigma_{inel} = 4\pi |f_0|^2 \frac{k'}{k}$$

$$b) \quad \left(e^{i\vec{k} \cdot \vec{x}} \right)_{l=0} = \frac{\sin kr}{kr} = \frac{e^{ikr} - e^{-ikr}}{2ikr}$$

$$\text{so } l=0 \text{ parts are } \psi_1 \sim -\frac{e^{-ikr}}{2ikr} + \frac{e^{ikr}}{r} \left(\frac{1}{2ik} + f_1 \right)$$

$$\psi_0 \sim \frac{e^{ikr}}{r} f_0$$

Clearly flux due to ψ_0 is $\frac{\hbar k'}{m} |f_0|^2 4\pi$ outwards.

$$\text{For } \psi = A \frac{e^{ikr}}{r} + B \frac{e^{-ikr}}{r}, \quad \psi^* \nabla \psi = \left(A^* e^{-ikr} + B^* e^{ikr} \right) ik \left(A e^{ikr} - B e^{-ikr} \right) \frac{1}{r^2} + O\left(\frac{1}{r^3}\right)$$

$$\text{so } \text{Im } \psi^* \vec{\nabla} \psi = \frac{\hbar}{r^2} k (|A|^2 - |B|^2) \text{ and flux} = \frac{\hbar k}{m} 4\pi (|A|^2 - |B|^2)$$

$$\text{So constraint is } k \left| \frac{1}{2ik} + f_1 \right|^2 + k' |f_0|^2 = \frac{k}{4k^2}$$

Clearly maximum σ_{inel} is when $f_1 = -\frac{1}{2ik}$

$$\text{when } k' |f_0|^2 = \frac{1}{4k} \text{ and } \sigma_{\text{inel}} = \frac{\pi}{k^2}$$

In that case $\sigma_{\text{el}} = \frac{\pi}{k^2}$ also.